

Electronics for IoT

H-Bridge

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DC Motor Control

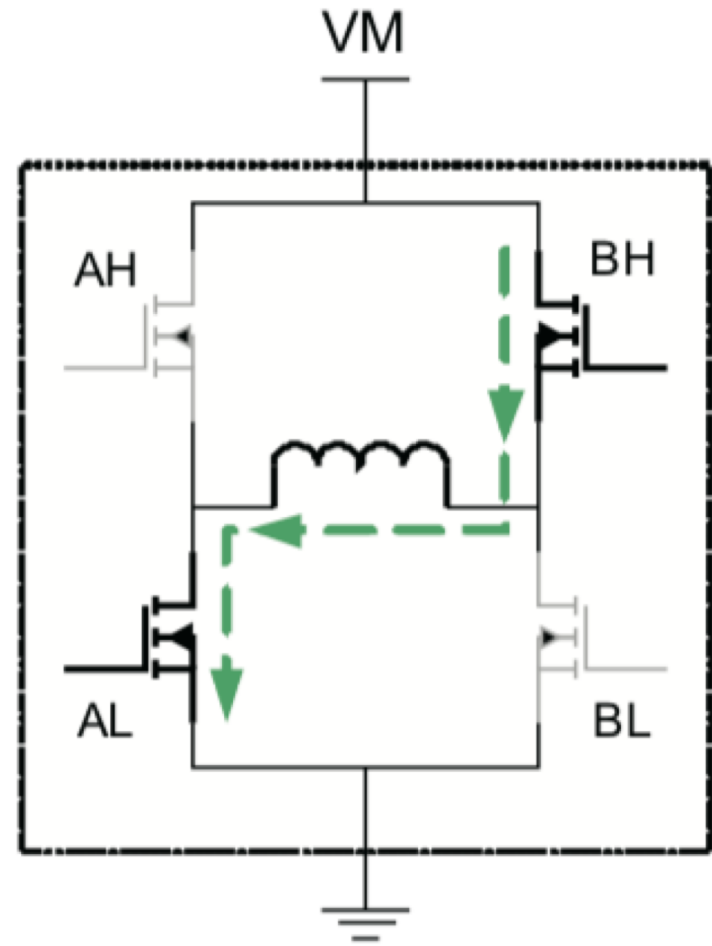
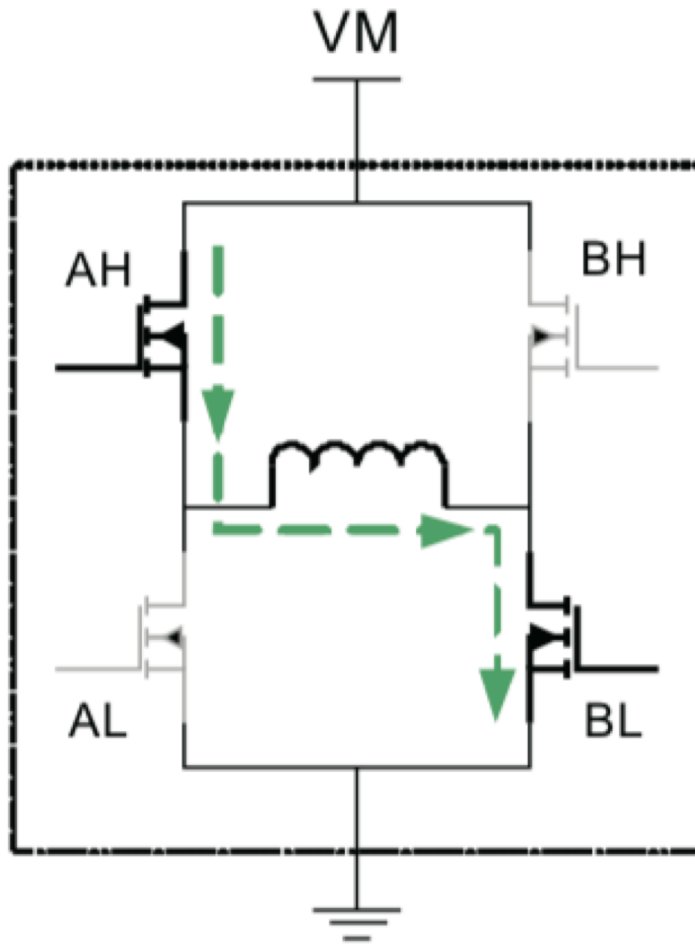
- Direction of Rotation
- Speed / Torque

On-Off Control

Direction of Rotation

<http://www.ti.com/lit/an/slva321/slva321.pdf>

H-Bridge



Turning Off ...

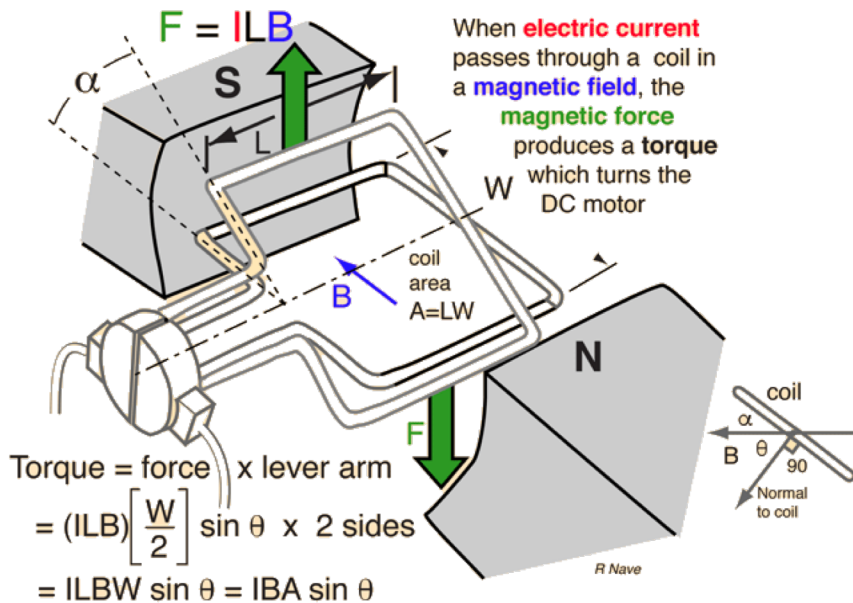


Attempt to “destroy” Energy



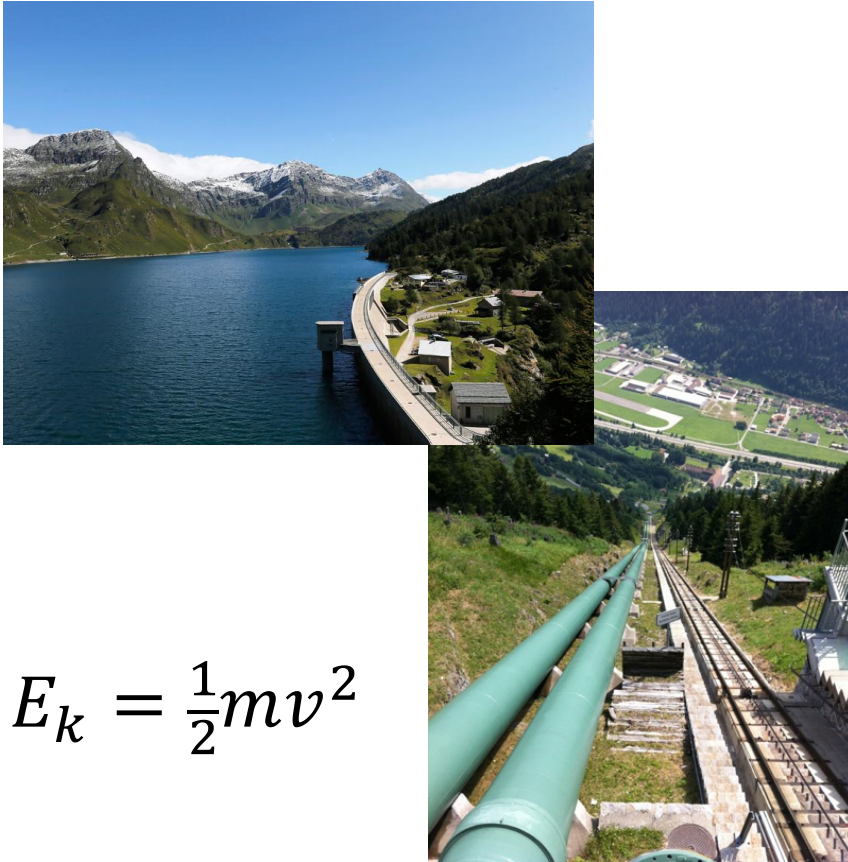
Motor: Energy

Magnetic Energy



Water / Current Analogy

Water: kinetic energy



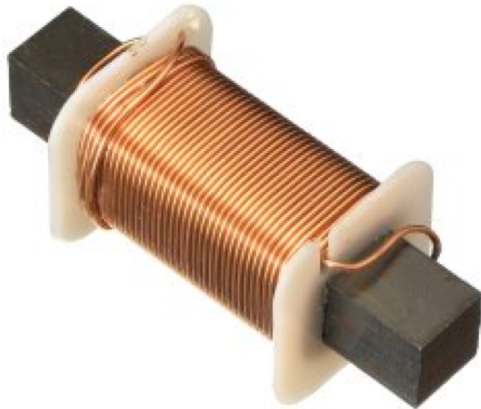
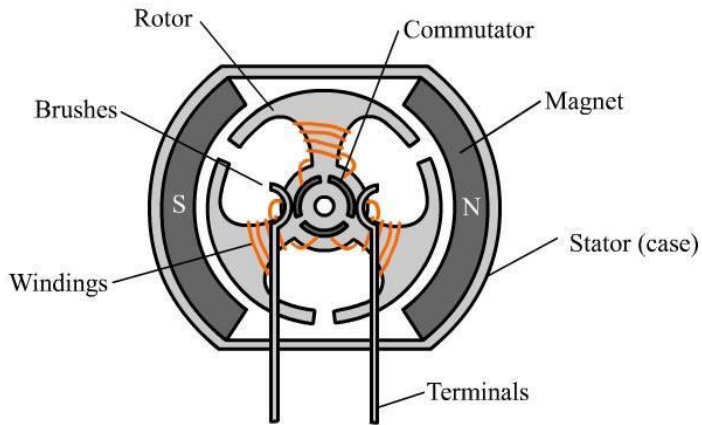
$$E_k = \frac{1}{2}mv^2$$

Current: magnetic energy

$$E_m = \frac{1}{2}Li^2$$

Inductance

Typical Brushed Motor in Cross-section



Calculate (just like inertia). E.g.

$$L = \frac{N^2 \mu A}{l}$$

$$\mu = \mu_r \mu_0$$

Where,

L = Inductance of coil in Henrys

N = Number of turns in wire coil (straight wire = 1)

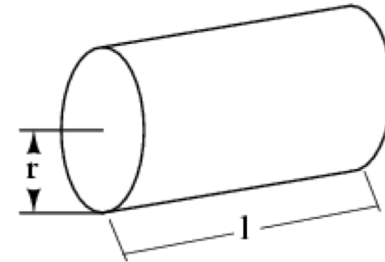
μ = Permeability of core material (absolute, not relative)

μ_r = Relative permeability, dimensionless ($\mu_0=1$ for air)

$\mu_0 = 1.26 \times 10^{-6}$ T-m/At permeability of free space

A = Area of coil in square meters = πr^2

l = Average length of coil in meters

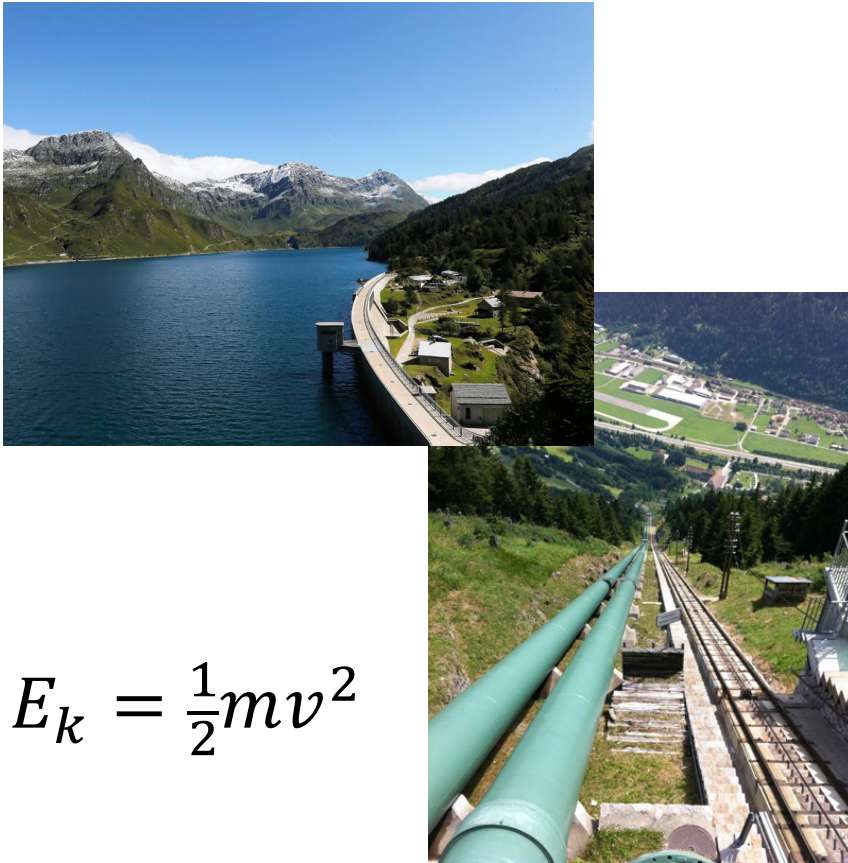


Finite element simulation for more complicated geometries

Inductor Symbol

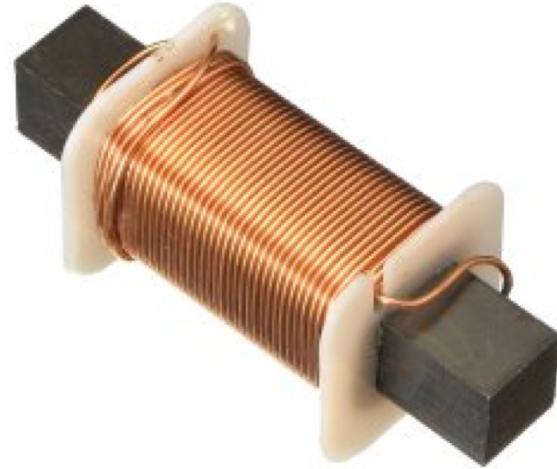
“Destroying” Magnetic Energy

Kinetic energy



$$E_k = \frac{1}{2}mv^2$$

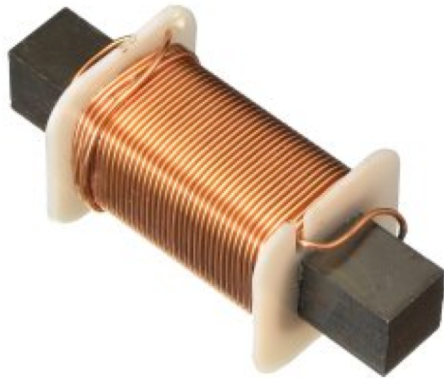
Magnetic energy



Inductor I/V Relationship

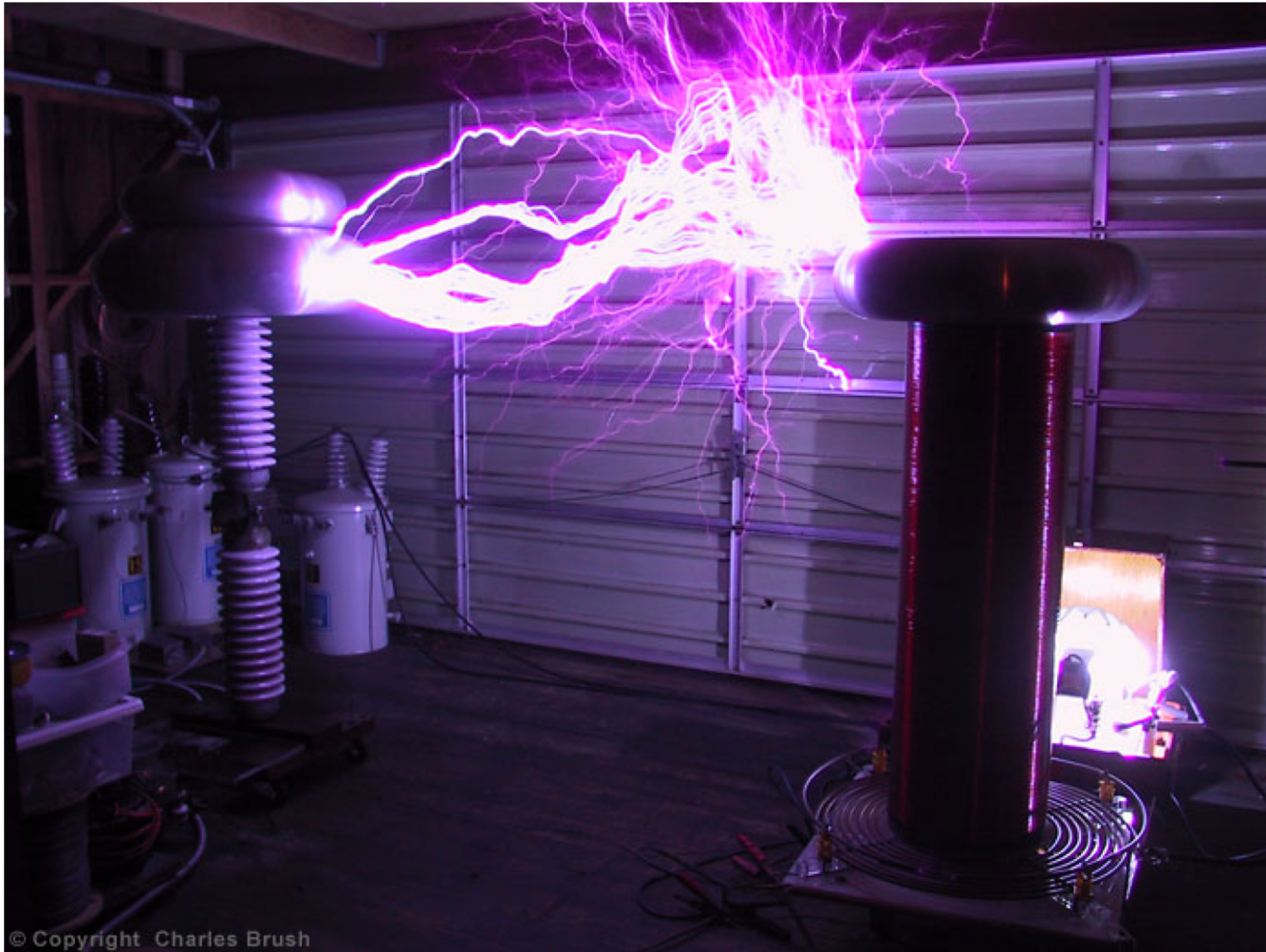
- Analogous to “Ohm’s Law”
 - But for inductors

Shutting off Inductor Current

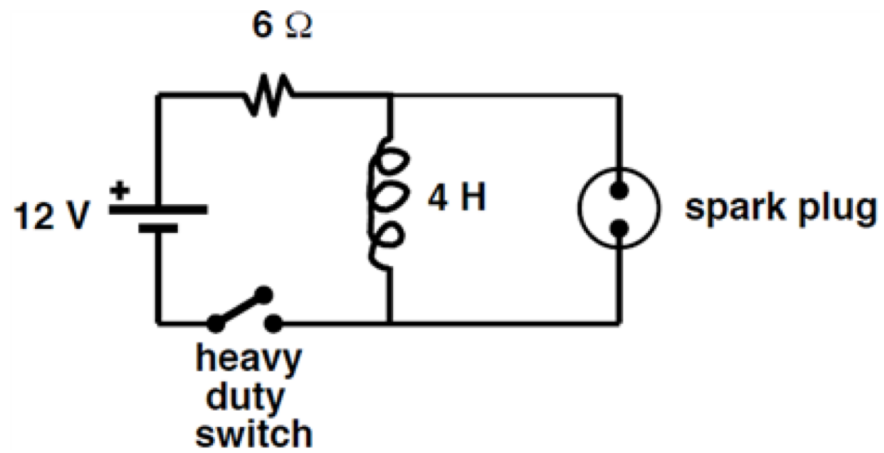


$$v = L \frac{di}{dt}$$

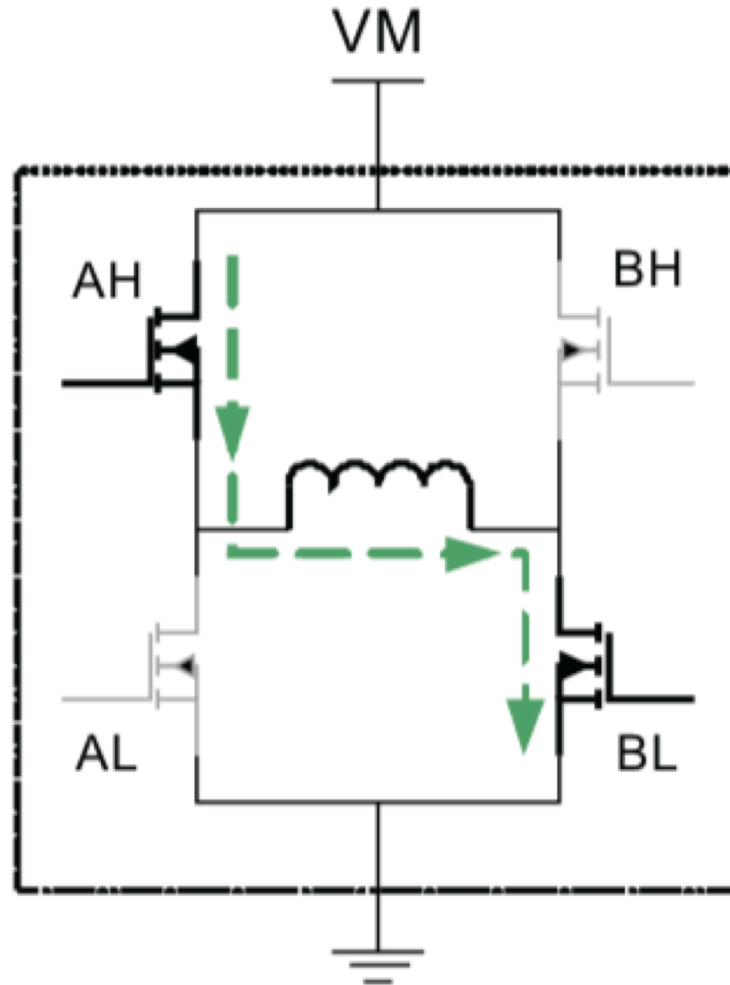
Tesla Coil



Spark Plug

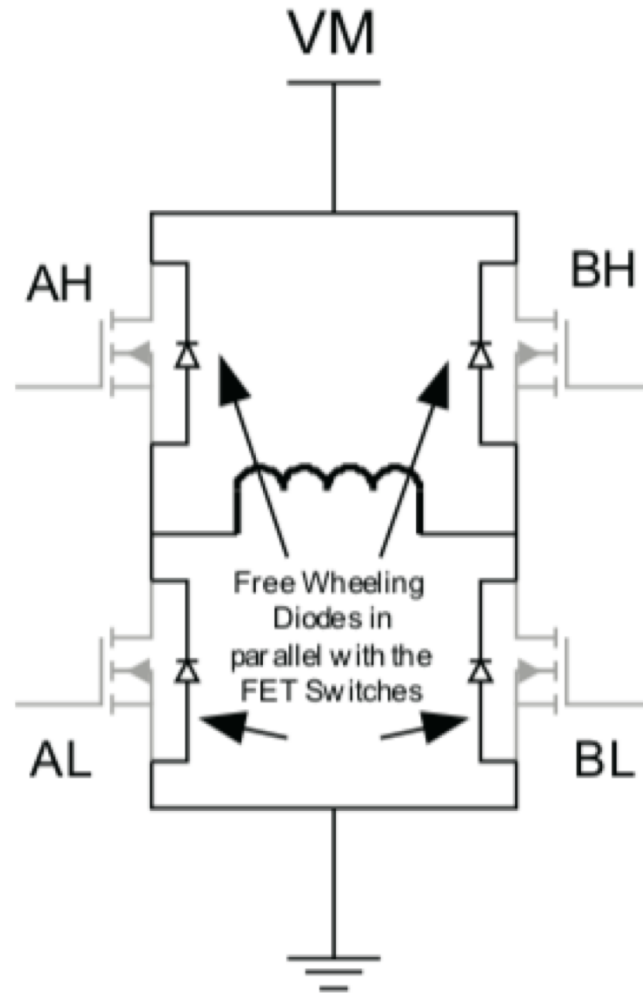


Water versus Current

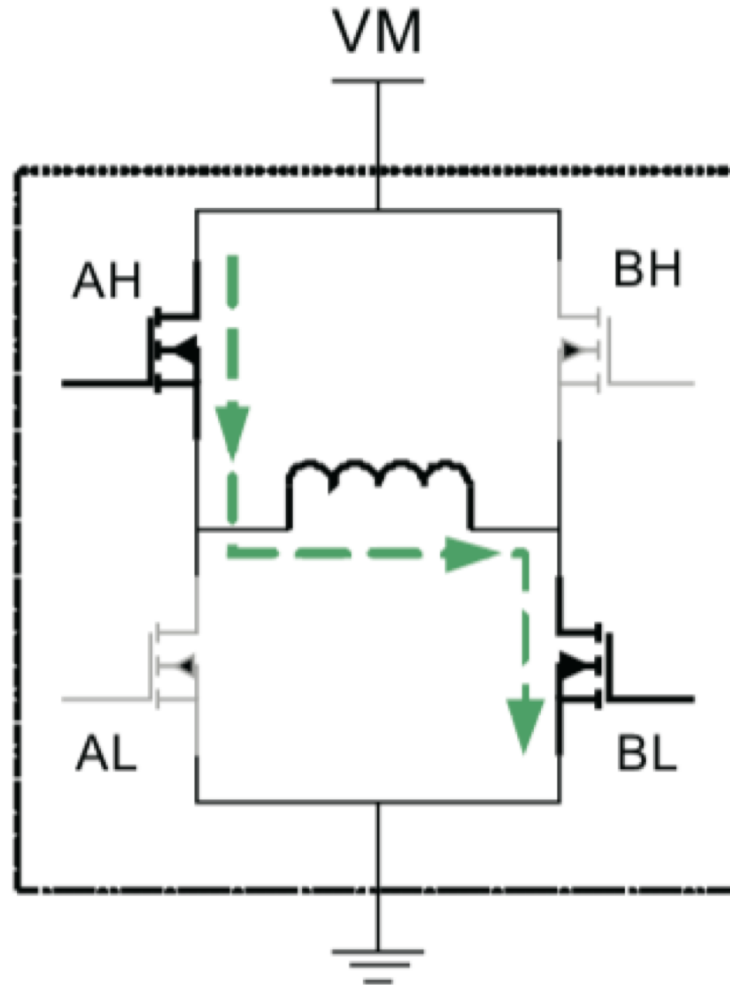


Diode

Free-Wheeling Protection Diodes

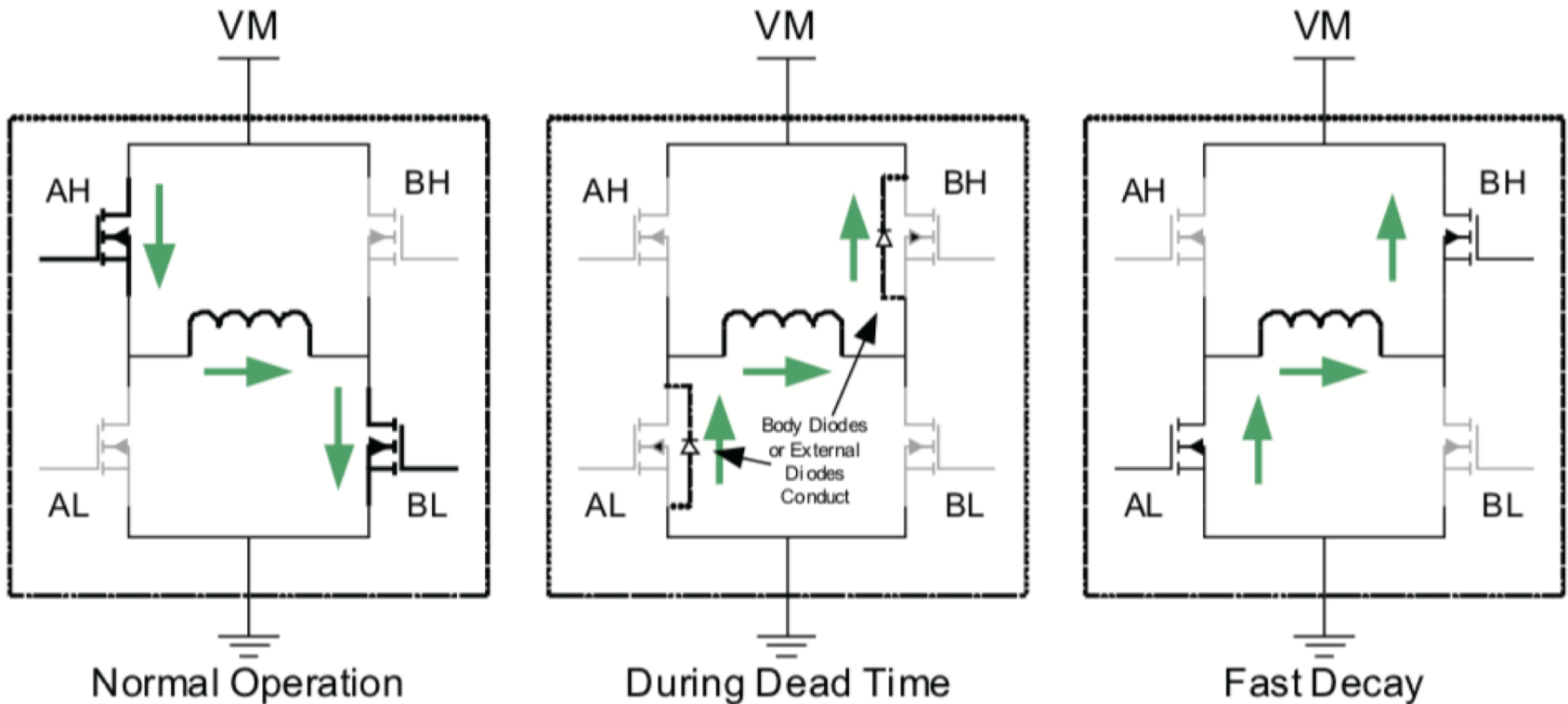


Speed / Torque Control

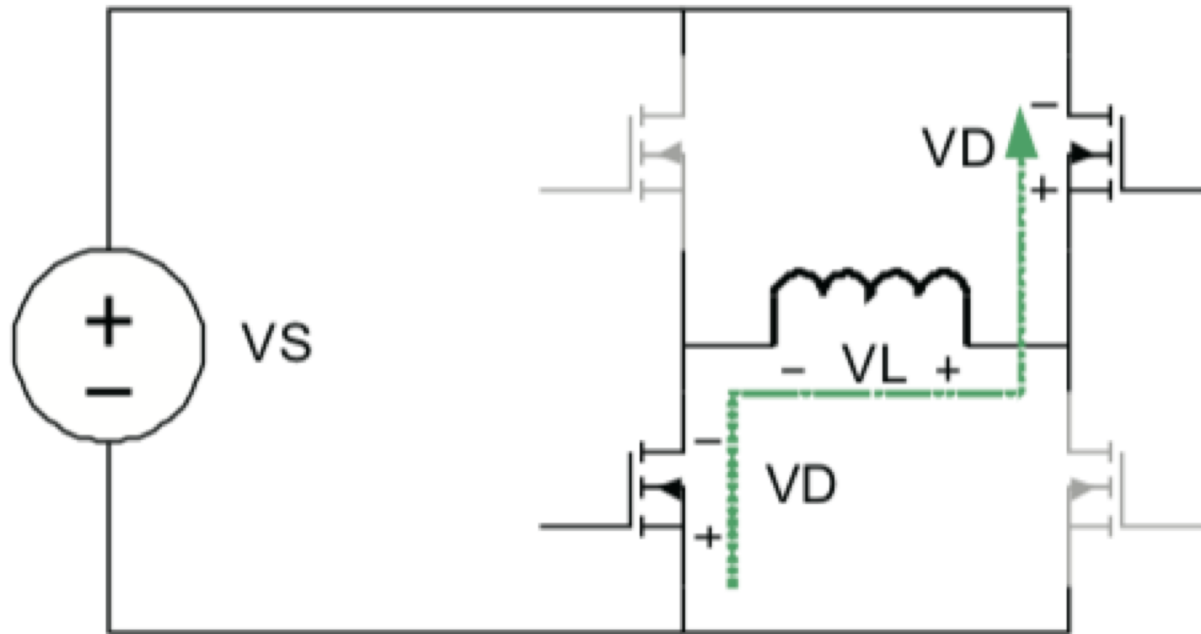


Switching “Off”

Fast Decay

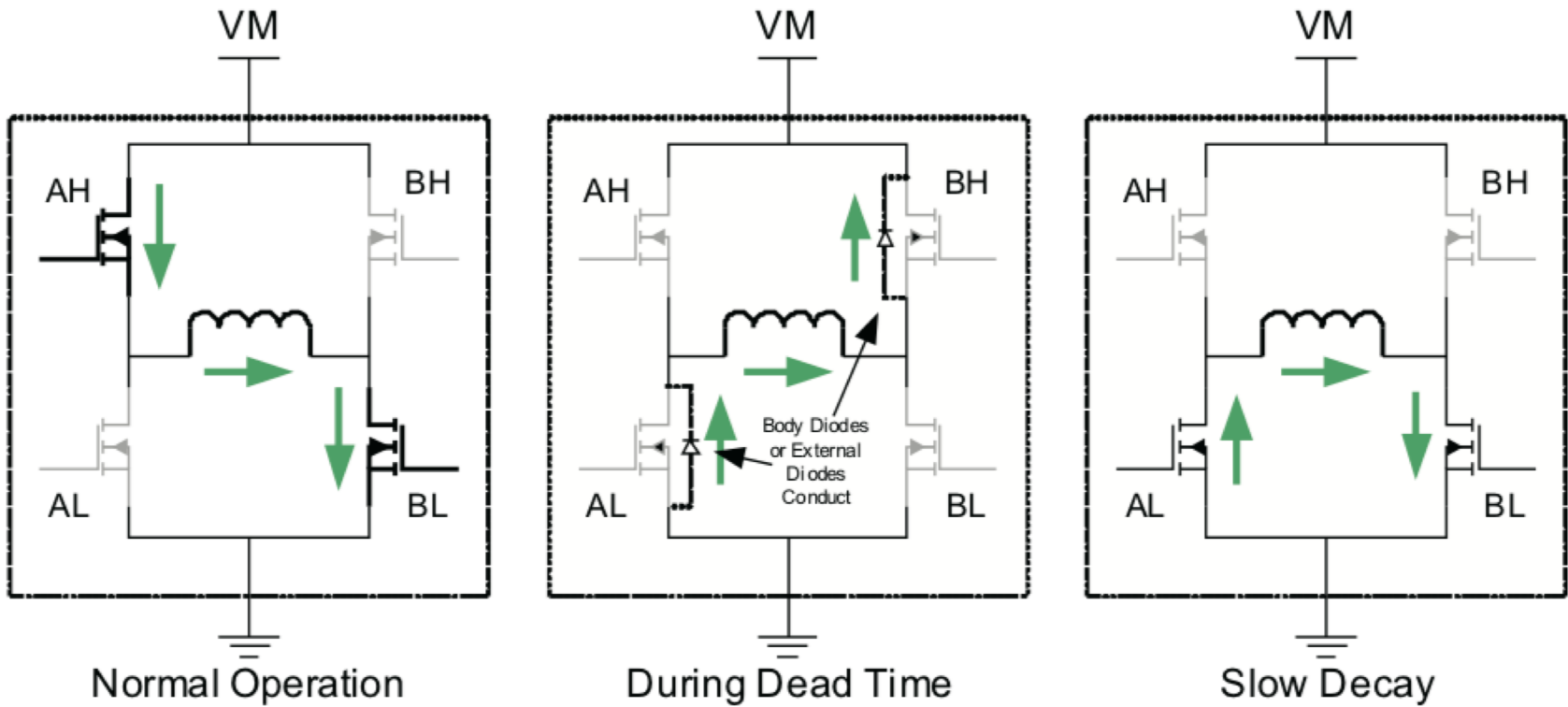


Fast Decay: Voltage across Motor

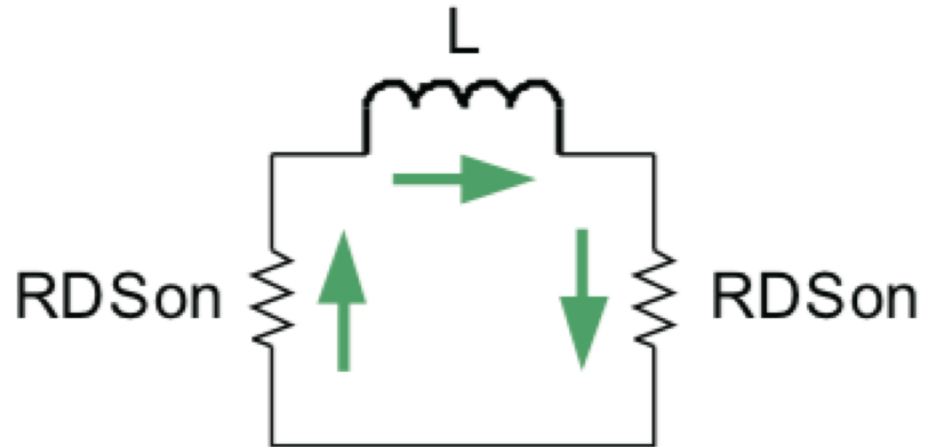


$$V_L = V_S + 2V_D$$

Slow Decay



Current Decay



Motor PWM Control

- Analogous to LED dimming

$$v = L \frac{di}{dt}$$

PWM Frequency

DRV8833



DRV8833

SLVSAR1E – JANUARY 2011 – REVISED JULY 2015

DRV8833 Dual H-Bridge Motor Driver

1 Features

- Dual-H-Bridge Current-Control Motor Driver
 - Can Drive Two DC Motors or One Stepper Motor
 - Low MOSFET ON-Resistance: HS + LS 360 mΩ
- Output Current (at $V_M = 5\text{ V}$, 25°C)
 - 1.5-A RMS, 2-A Peak per H-Bridge in PWP and RTY Package Options
 - 500-mA RMS, 2-A Peak per H-Bridge in PW Package Option
- Outputs can be in Parallel for
 - 3-A RMS, 4-A Peak (PWP and RTY)
 - 1-A RMS, 4-A Peak (PW)
- Wide Power Supply Voltage Range: 2.7 to 10.8 V
- PWM Winding Current Regulation and Current Limiting
- Thermally Enhanced Surface-Mount Packages

3 Description

The DRV8833 device provides a dual bridge motor driver solution for toys, printers, and other mechatronic applications.

The device has two H-bridge drivers, and can drive two DC brush motors, a bipolar stepper motor, solenoids, or other inductive loads.

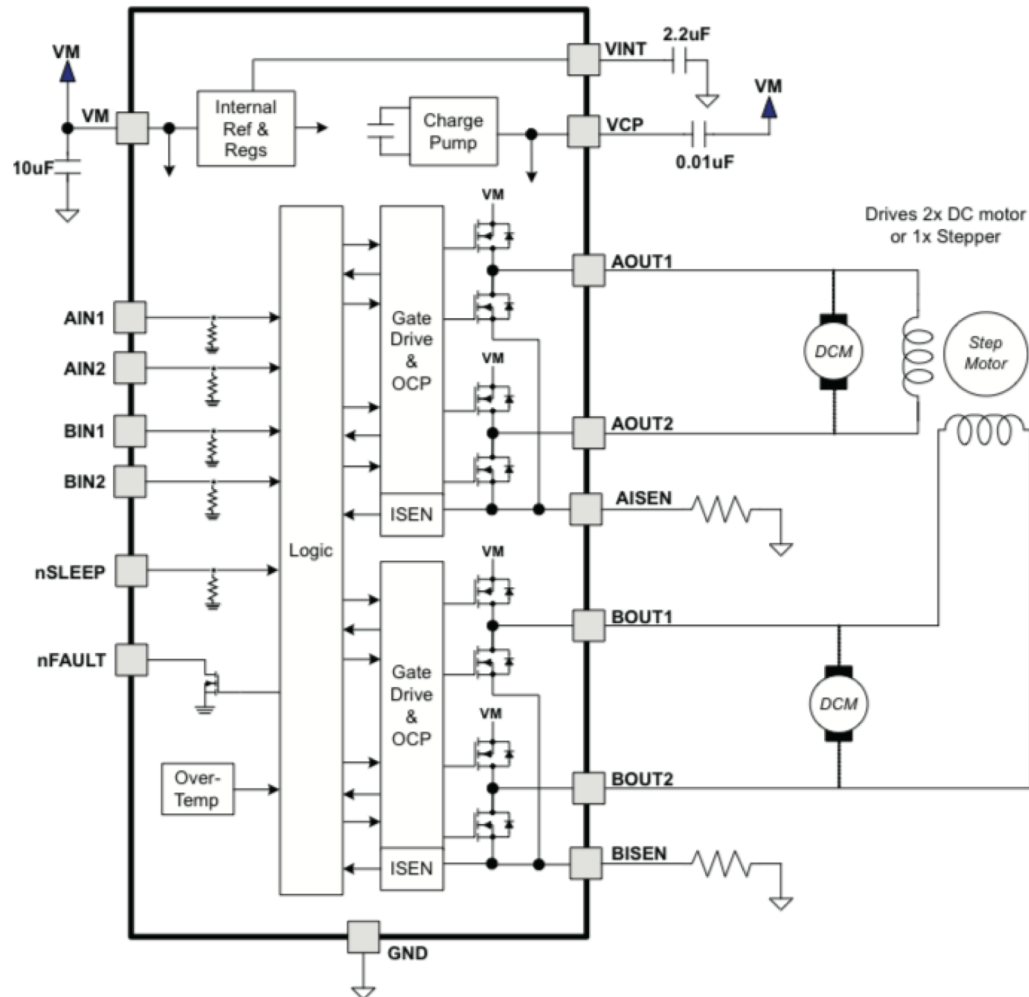
The output driver block of each H-bridge consists of N-channel power MOSFETs configured as an H-bridge to drive the motor windings. Each H-bridge includes circuitry to regulate or limit the winding current.

Internal shutdown functions with a fault output pin are provided for overcurrent protection, short-circuit protection, undervoltage lockout, and overtemperature. A low-power sleep mode is also provided.

The DRV8833 is packaged in a 16-pin WQFN package with PowerPAD™ (Eco-friendly: RoHS & no Sb/Br).

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Block Diagram



Direction Control

Table 1. H-Bridge Logic

xIN1	xIN2	xOUT1	xOUT2	FUNCTION
0	0	Z	Z	Coast/fast decay
0	1	L	H	Reverse
1	0	H	L	Forward
1	1	L	L	Brake/slow decay

PWM Control

Table 2. PWM Control of Motor Speed

xIN1	xIN2	FUNCTION
PWM	0	Forward PWM, fast decay
1	PWM	Forward PWM, slow decay
0	PWM	Reverse PWM, fast decay
PWM	1	Reverse PWM, slow decay

PWM Signals

Table 2. PWM Control of Motor Speed

xIN1	xIN2	FUNCTION
PWM	0	Forward PWM, fast decay
1	PWM	Forward PWM, slow decay
0	PWM	Reverse PWM, fast decay
PWM	1	Reverse PWM, slow decay

Summary

- H-bridge
 - Motor speed
 - Direction
- Magnetic energy, inductance
- PWM
 - Torque / speed control
 - PWM Frequency
- Magnetic energy management
 - Freewheeling diodes
 - Fast decay
 - Slow decay